

Control valve design aspects for critical applications in petrochemical plants – part II

By Dipl. Ing. Holger Siemers, SAMSON AG

This second section of Mr Holger Siemers article on control valve design and sizing continues on from part I, which can be found in the June 2004 issue of Valve World. This section presents information on design, size and use of severe service control valves, the kind of troubles that can be predicted with control valve sizing as well as suggestions for troubleshooting control valve failures. The final section, part III, will be ready and waiting in the upcoming October issue.

4) Predictable troubles with control valve sizing in case of sub-critical flow conditions

It is well-known that sensitive valve sizing areas exist with supercritical gases and slightly sub-cooled or non-sub-cooled liquids (flashing). Vapors and gases are calculated with the isentropic exponent k as one of the property values. Some hydrocarbons, e.g. ethylene, are near or above the “critical points t_{crit} and p_{crit} ” during the process.

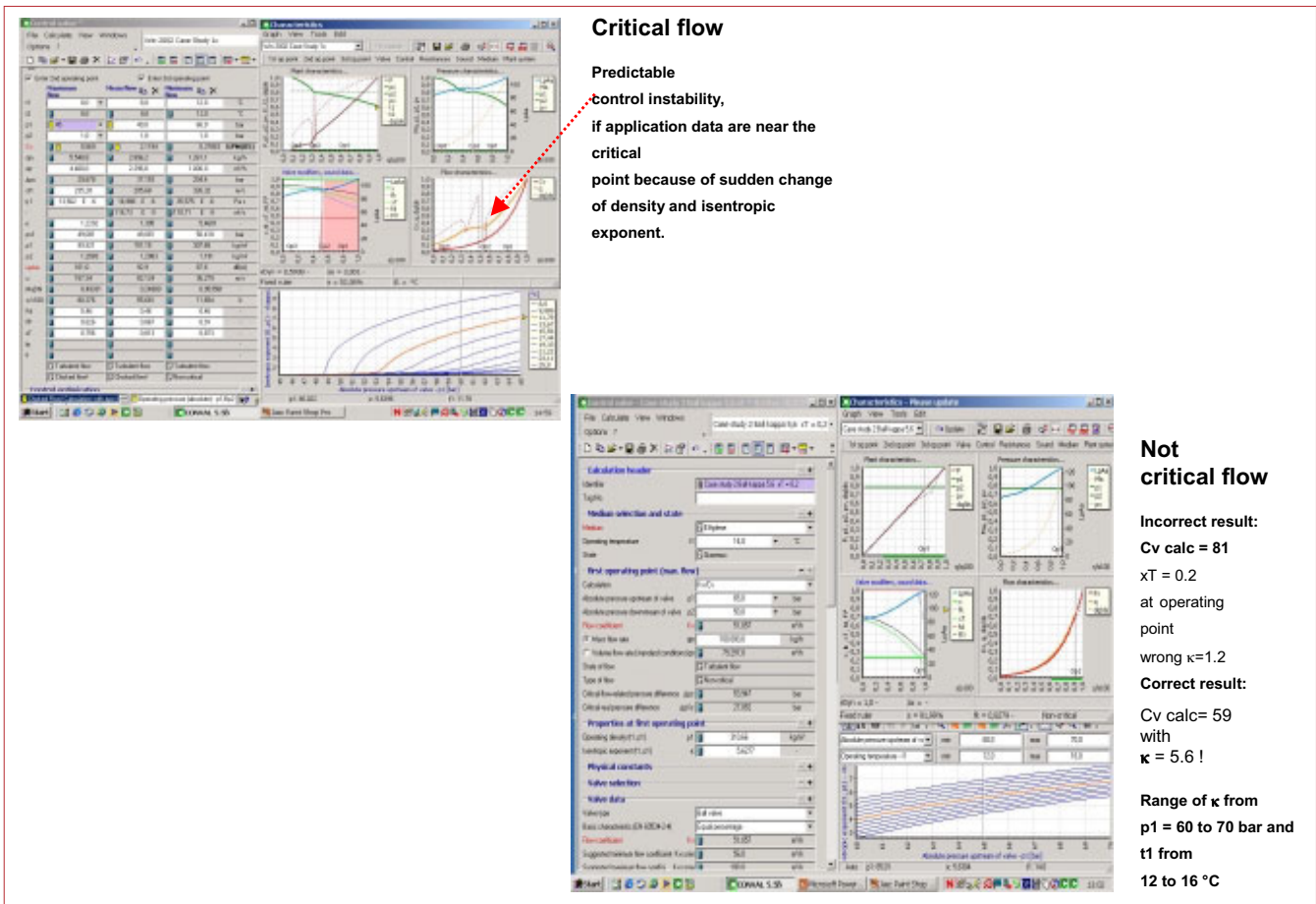


Fig. 16: Sensitive sizing areas in case of supercritical flow “isentropic exponent above the critical point” > 2

The sizing standard IEC 60534 2-1 includes an information table with typical isentropic exponents used for steam and gas sizing. The total range $1 < k < 2$ is well-known for all compressible fluids. However, it is less-well-known that values $2 < k < 20$ exist with supercritical fluids near and above the property critical point.

We would like to introduce this matter with the help of latest development in precise property calculation, published at the Ruhr University of Bochum for more than 60 industrial gases and integrated into the CONVAL™ software.

The third case study shows tremendous sizing differences in flow calculation for an ethylene

application at the critical point of properties by using the real isentropic exponent $\gg 2$. This can have a negative influence on plant safety valves and other devices. In the past, devices for supercritical flows were oversized because the wrong isentropic exponents and “choked flow limits” were used. We are interested to start an open discussion on how to define and handle this phenomenon and on how to validate it with measurements.

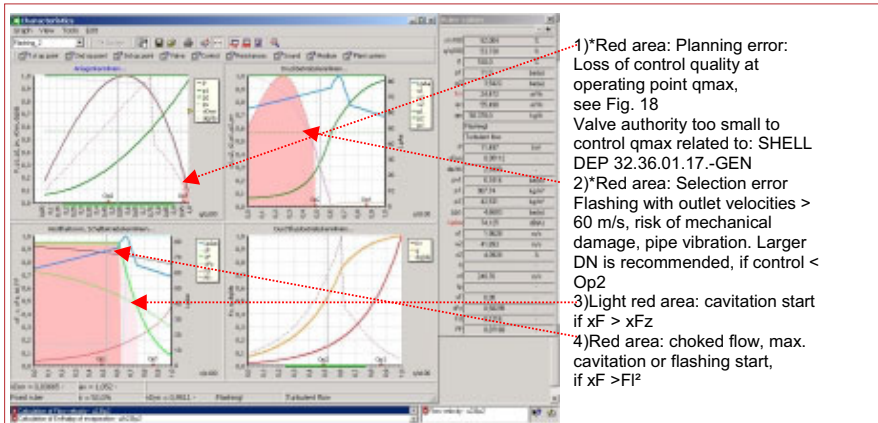


Fig. 17: Example of warning indicators in a hot water application to indicate the onset of cavitation and flashing at smaller loads. If not controlled below Op2 no risk, if often control smaller loads $< Op2$, valve DN too small.

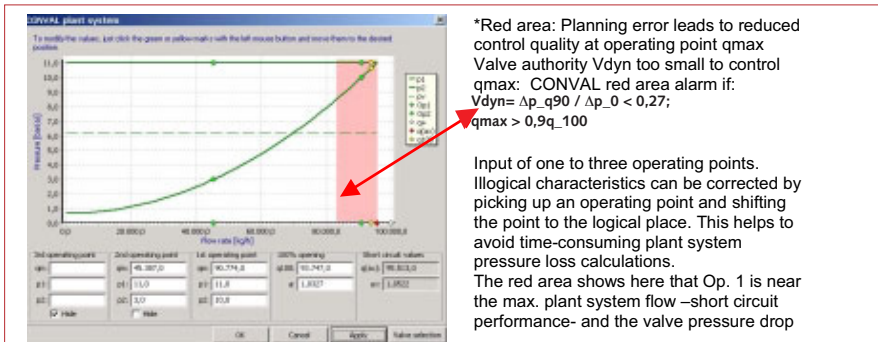


Fig. 18: Dynamic plant system: – pressure versus flow-
*Red area: Planning error: Loss of control quality at operating point q_{max} . Valve authority too small to control q_{max} . Optimised, following: SHELL DEP 32.36.01.17.-GEN (Design and Engineering Practise)

1-Butene	Diethylether	Isohexan	Pentane	R125
Air	Diisopropyl	Isopentan	Phenol	R134a
Ammonia	Dipropylether	Krypton	Propane	R141b
Argon	Ethane	Methane	Propylbenzol	R142b
Benzene	Ethylbenzol	Methanol	Propylene	R143a
Butane	Ethylene	Natural gas	SF6	R152a
Carbon monoxide	Fluorine	(AGA8)	Toluene	R218
Carbon dioxide	Helium	Neon	Water	R22
Chlorine	Heptane	Neopentan	Xenon	R23
Cyclohexane	Hexane	Nitrogen	R11	R32
Cyclopentan	Hydrogen	Nitrous oxide	R113	R41
Cyclopropan	Hydrogensulphi	Nonane	R12	
Decane	de	Octane	R123	
	Isobutane	Oxygen	R124	

Table 3: Available substances calculated with thermodynamic equations



Fig. 19: Typical damage due to cavitation if pressure differential > 20 bar. Feedwater control valve mismatched for start-up 70 to 1 bar.



Fig. 20: Damage due to flashing if $p_2 \ll p_v$ and $v_2 \gg 60$ m/s.



Fig. 21: Damage due to a rotary plug body due to cavitation $v_2 \gg 5$ m/s.

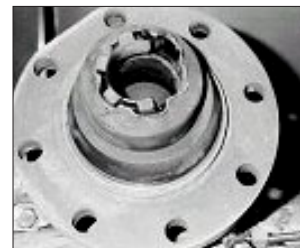


Fig. 22: Damage due to steam pressure letdown $Ma \gg 1$.

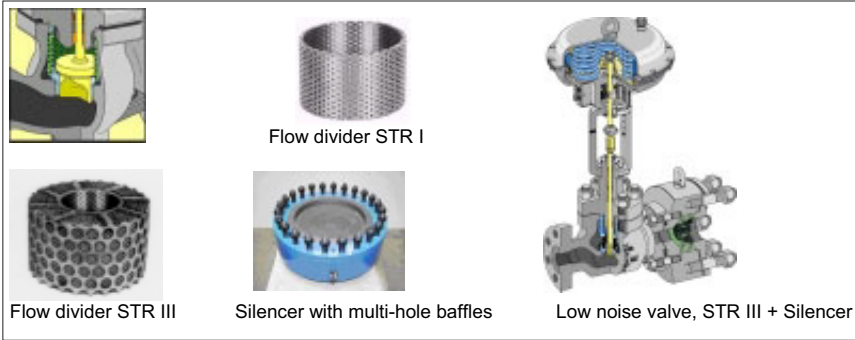


Fig. 23: The simplified noise abatement system used for compressible fluids.

Predictable troubles with control valve sizing in case of flashing as well as installation cost saving which results in poor planning parameters

Figure 17 shows an example of warning indicators in a hot water application to indicate the onset of cavitation and flashing at smaller loads. If not controlled below Op_2 no risk, if often control smaller loads $<Op_2$, valve DN too small.

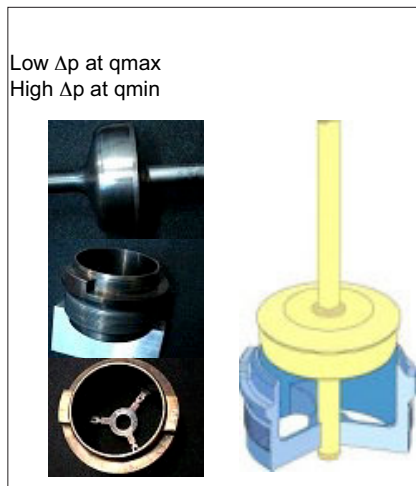


Fig. 24: AC Trim I System.

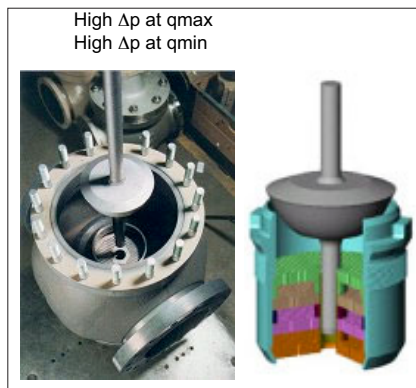
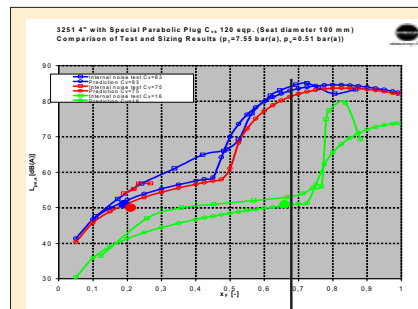


Fig. 25: AC Trim II System

CONVAL calculates real thermodynamic flashing conditions with about sixty hydrocarbons [see Table 3] and recommends the minimum valve DN to avoid critical outlet velocities. The calculations resemble steam table mathematics. This is based on a reliable source,



AC Trim I System
Application with:
Low Δp at q_{max}
High Δp at q_{min}

Fig. 26: Case history: application with low Δp at q_{max} and high Δp at q_{min} . Troubleshooting for an acetic acid plant, replaciong a noisy cage valve $>> 85 \text{ dB(A)}$ at a petrochemical plant in Hull (UK) with an AC Trim I System. The requirements were to avoid cavitation in the range of control in case of corrosive fluids. $X_{Fz} > 0.75$ at critical min. flow.

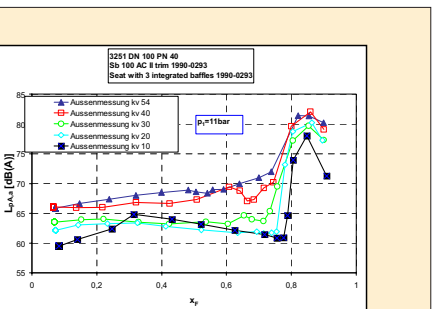
the "Lehrstuhl für Thermodynamik Fakultät für Maschinenbau der Ruhr-Universität Bochum"
www.ruhr-uni-bochum.de/themo/index-eng.htm

Installation cost saving which results to poor planning parameters

Detecting planning mistakes: $q_{max} > 0.9 q_{100}$, Δp at q_{max} too small. See Figure 18.

5) Control valve failure and troubleshooting.

Ranging from seat guided V-port to CFD optimized trims and their applications. There are different solutions to avoid critical sound and mechanical valve failure (see Figures 19 through 22). This section introduces anti-cavitation valve trim designs [2] and noise attenua-



AC Trim II System
Application with:
Low Δp at q_{max}
High Δp at q_{min}

p1 [bar]	11	11	11
p2 [bar]	4	4	4
pv [bar]	0.01	0.01	0.01
Q [m³/h]	30	108	144
rho [kg/m³]	835	835	835
kv ges [m³/h]	10.36	37.3	49.73
Lp [dB(A)]	< 70	< 70	< 70
xF	0.64	0.64	0.64

Fig. 27: Case history: application with high Δp at q_{max} and high Δp at q_{min} . Troubleshooting for a gasoline loading station at a refinery in Hamburg (Germany) with AC Trim II System and the requirement to reduce SPL $> 90 \text{ dB(A)}$ to $< 70 \text{ dB(A)}$ in the entire range of control. $X_{Fz} > 0.75$ in the total range of control.

Globe valve type	X_{Fz} for valve 75% load	X_{Fz} for valve $<< 75\%$ load	Resistance to contamination	Vibration behavior
Parabolic plug	0.25 to 0.35	clearly up to 0.8	high	poor for single-guided plugs
Piston-balanced plug with cage	0.25 to 0.35	up to 0.5	low	good
V-port plug	0.25 to 0.35	up to 0.5	high	excellent
Perforated plug	0.25 to 0.35	0.25 to 0.35	low	good
AC Trim System	0.35 to 0.5	clearly up to 0.85	high	good

Table 4: Different trim designs and their advantages and disadvantages in severe service applications.

tion devices and discuss their advantages and disadvantages as well as their application limits. Note that too high velocities at the valve moving parts and at valve outlet are mainly responsible for valve failure especially where corrosive fluids are handled.

SAMSON AG offers under strong limitations of valve outlet velocities and other parameters the high performance V-port trim for general service; flow dividers I and III and downstream low noise devices for gas and steam pressure letdown. See Figure 23.

If the V-port trim sound pressure level (SPL) is not acceptable for liquid applications or cavitation and corrosion must be avoided in general, the unique AC Trim System is recommended (see Figures 24 and 25) with top and seat guided plug; it is vibration-free and dirt-insensitive. The max. pressure differential 25 to 40 bar depends on the fluid properties. For case histories of troubleshooting with the AC Trim sys-



Fig. 28: AC Trim III System.

tem, please see Figures 26 and 27. Further, Table 4 gives an overview of the advantages and disadvantages of different trim designs.

AC Trim III system multistage design

The AC Trim III System is ideal for liquid application to avoid cavitation, wear and noise (see Figure 28). Features include top and seat guided plug, vibration free and dirt-insensitive, with/without pressure balance, pressure differential 25 up to 120 bar; AC Trim V System-5 stages-120 bar <math>\Delta p < 200 \text{ bar}</math>. Three and five stages in the cv range from $C_v = 1$ (3 stages) to $C_v = 116$ from DN 1 to DN 6 inch in globe and angle type valves are used in case of severe cavitation problems e.g. high Δp together with a larger control range q_{min} to q_{max} . Typical applications are feed-water start-up valves, refinery valves, snow gun valves, injection valves, boiler applications, high pressure letdown service, etc.

6) The hidden valve enemy: Critical outlet velocities need to take priority

Beating “quick and dirty” sizing philosophies, if selecting too small valve DN taking only the calculated C_v value into account. High flow capacity valves (C_v/DN^2) need to be selected with care when critical operation conditions are involved. Rule of thumb to avoid mix phase flow: in case of p_v equal or near to p_1 avoid $20 \times DN$ any pipe restriction at valve upstream, no elbows, no manual valves, no pipe reducers.

Sensitive sizing areas special valve DN selection by giving priority to the outlet velocity condition of cavitation and flashing in liquid application and gas and steam pressure letdown, taking important piping parameters into account.

In case of flashing conditions, the average outlet velocity has to be calculated for the mixture of liquid and wet steam or vapour. Severe pipe vibration and valve damage can be avoided if the valve outlet diameter restricts the outlet velocity to less than 60 m/s (average of 0.7 Ma of mixture sonic speed). SAMSON has developed equations of state for flashing outlet velocities used in CONVAL for all fluids in Table 3.

To be continued.

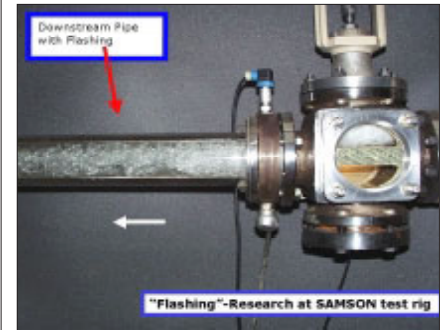


Fig. 29: Flashing Photo SAMSON AG test rig [2]

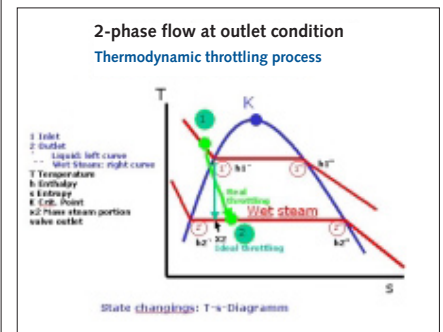


Fig. 30: The thermodynamic flashing process. T = temperature; s = entropy; K = critical point.



Fig. 31: Plant shutdown due to “quick and dirty” sizing with 8 inch rotary plug valve and too small DN.

Non-subcooled naphtha $p_1 = p_v$. The application requires a 12 inch valve to avoid the risk of sonic speed “choked flow” at the valve outlet.

Valve design	K_c	$\Delta p_{crit,cav}$ [bar]
Single-stage globe valves with stellite or hardened valve plug and seat	0.7	25
Single-stage globe valves with standard materials	0.7	15
Rotary plug valves (with eccentric spherical disk)	0.4	10
Butterfly and ball valves	0.2-0.3	5

Table 5: Recommendations to reduce cavitation erosion [2]. Using table 5 for non-corrosive liquids with cavitation: $X_F > X_{Fz}$

- Outlet velocity should not exceed 2m/s to max 5m/s depends on valve design
- Low vibration valve plug design like seat, cage or top and bottom guided plugs.
- Low cavitation erosion: $\Delta p < K_c \cdot (p_1 - p_v)$ or $\Delta p < \Delta p_{crit,cav}$, if $\Delta p > K_c \cdot (p_1 - p_v)$!
- Cavitation erosion: $\Delta p > K_c \cdot (p_1 - p_v)$ and $\Delta p > 25 \text{ bar}$ -> multistage globe valves (like AC Trim III System)